

CONTROL OF CONVERTERS IN WIND TURBINES

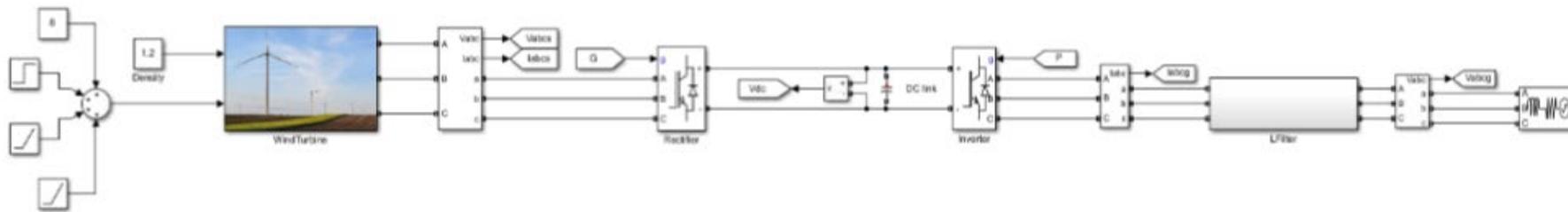
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- Raising fear of climate changes -> bigger use of renewable energy sources
- These sources are more or less stochastic -> necessary to use power converters in order to adopt their volatility
- Converters were not efficient enough – huge improvements have been made in recent period
- Today, power converters perform all the necessary functions with minimal response time and energy consumption

- The converter consists of several parts
- On the machine-turbine side, we use a rectifier based on IGBT transistors, controlled using pulse-width modulation
- The machine we use in this simulation is an induction generator, as it is easiest to place in a wind turbine and it is connected to the wind turbine via a gearbox
- Further, the converter contains a single capacitor (DC link)
- Finally, we use an inverter based on IGBT transistors, controlled by pulse-width modulation



Discrete to Ck s
power



a/c Reference



DQ Transformation



D Reference



GSC



GSI

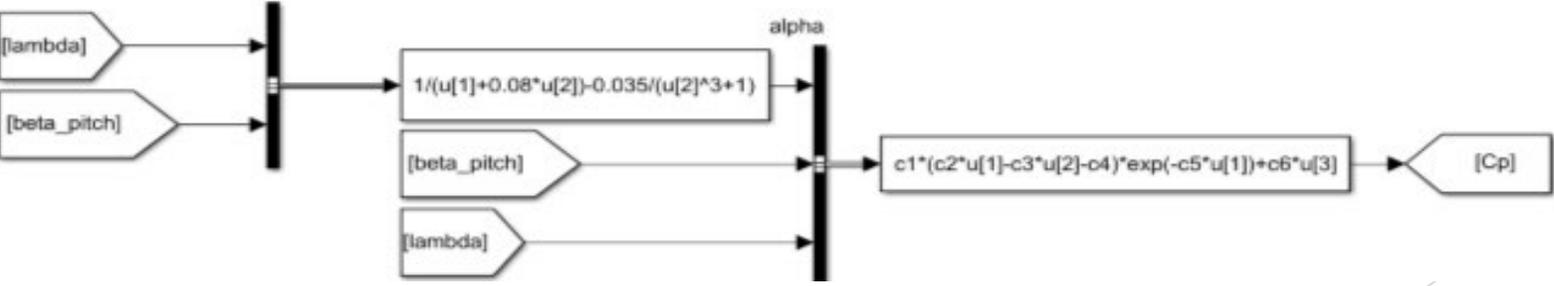
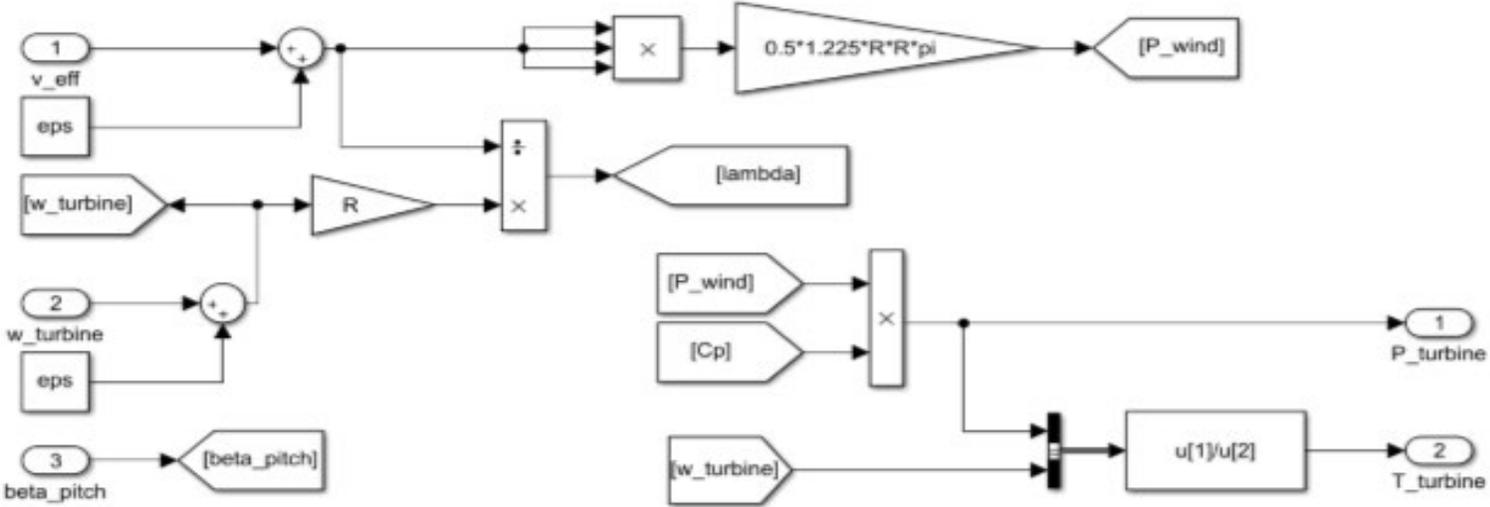
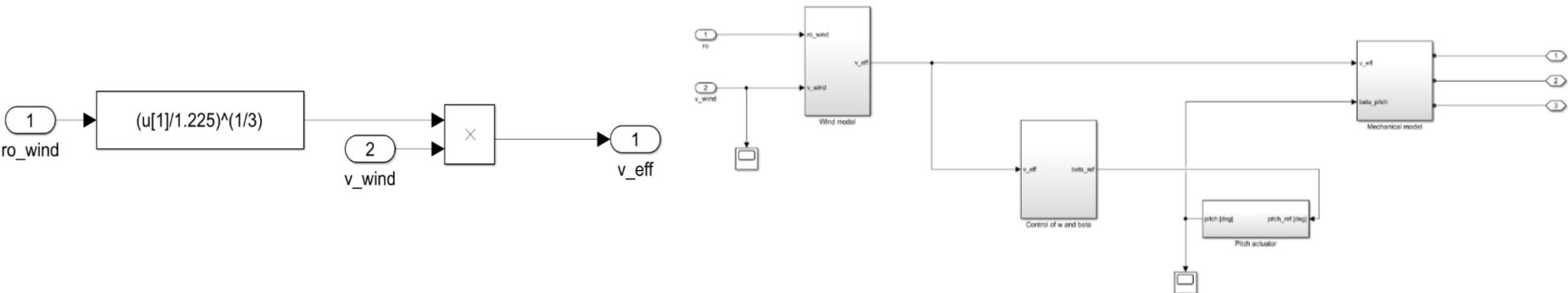


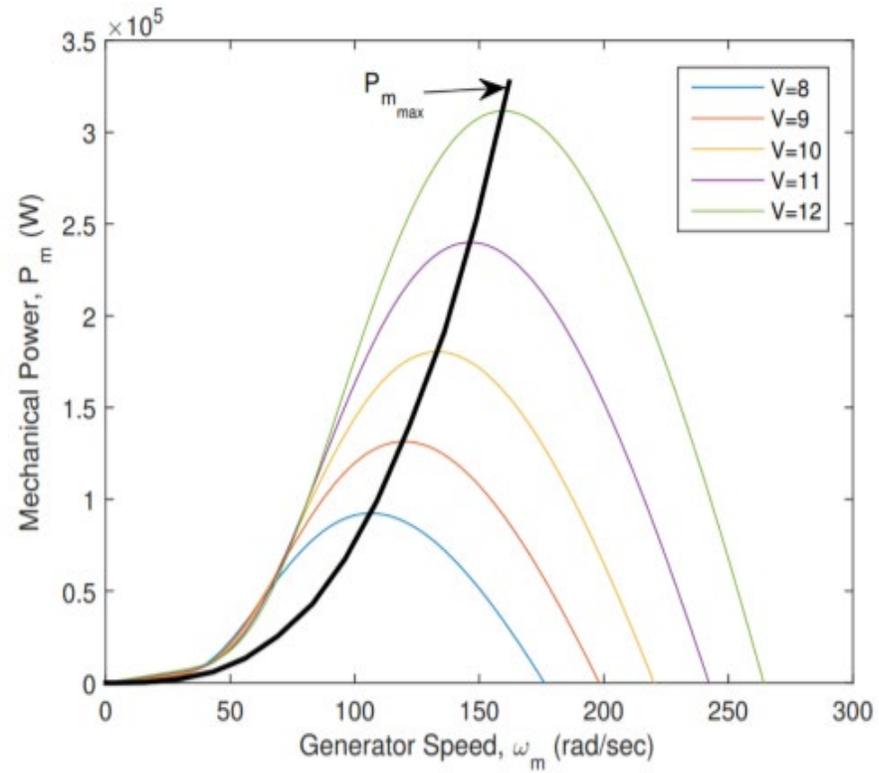
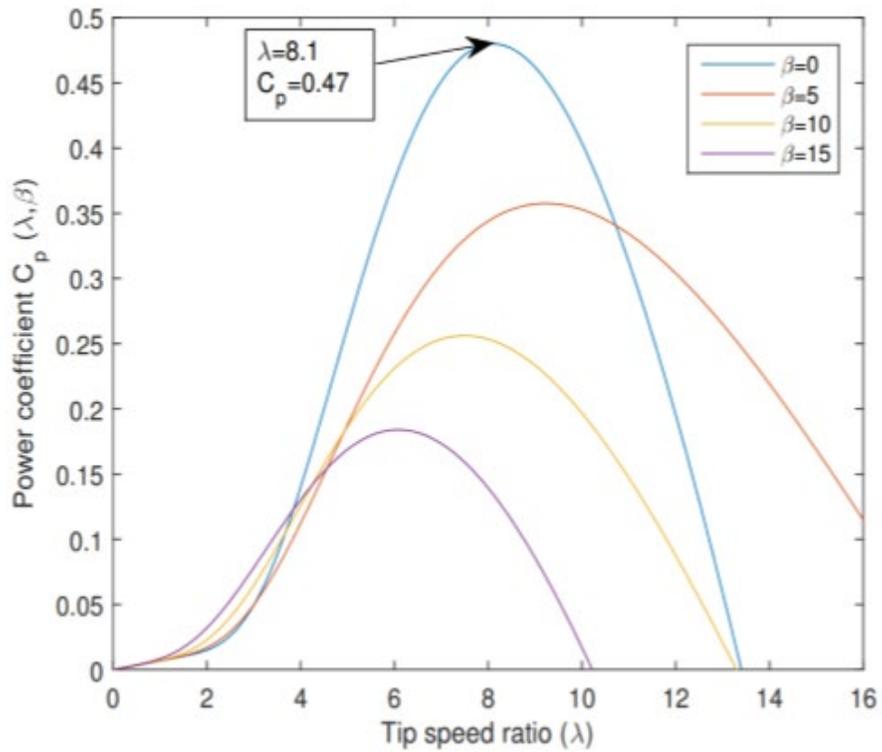
PLL



Scope

Windturbine Model

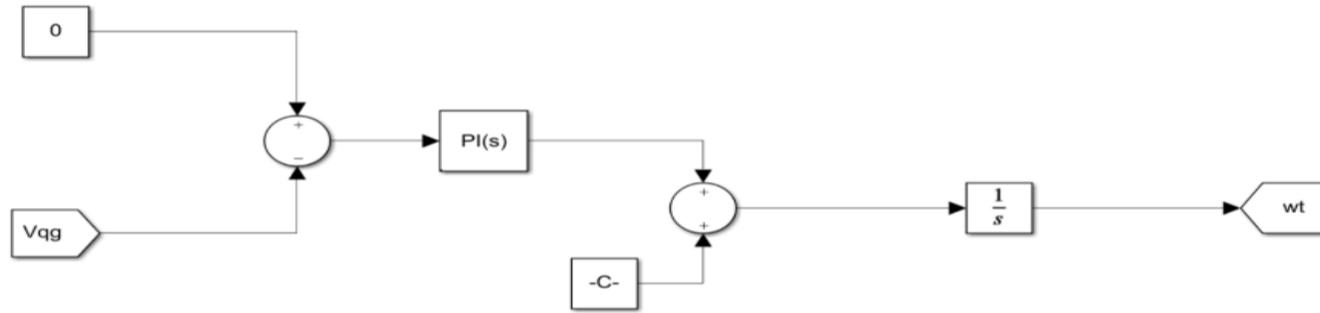




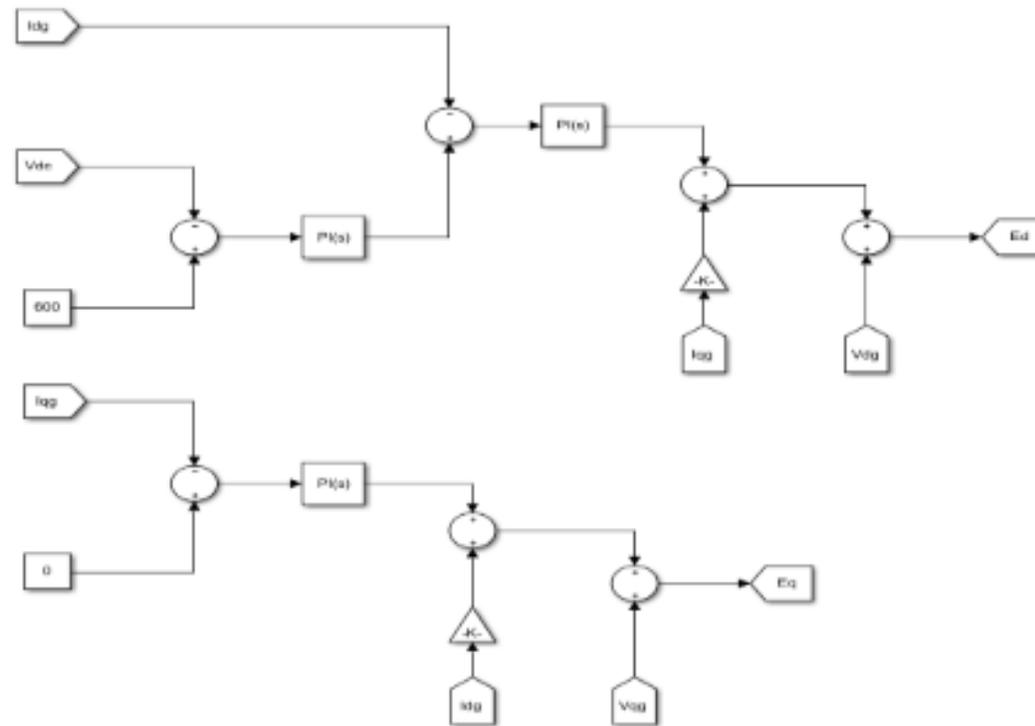
- The mechanical power is $P_m = 0.5 * C_p(\lambda, \beta) * \rho * A * v^3$
 where C_p is the power coefficient of wind turbine that can be expressed as

$$C_p(\lambda, \beta) = a_1 * \left(\frac{a_2}{\lambda} - a_3 * \beta - a_4 \right) * e^{\frac{(-a_5)}{\lambda}} + a_6 * \lambda$$

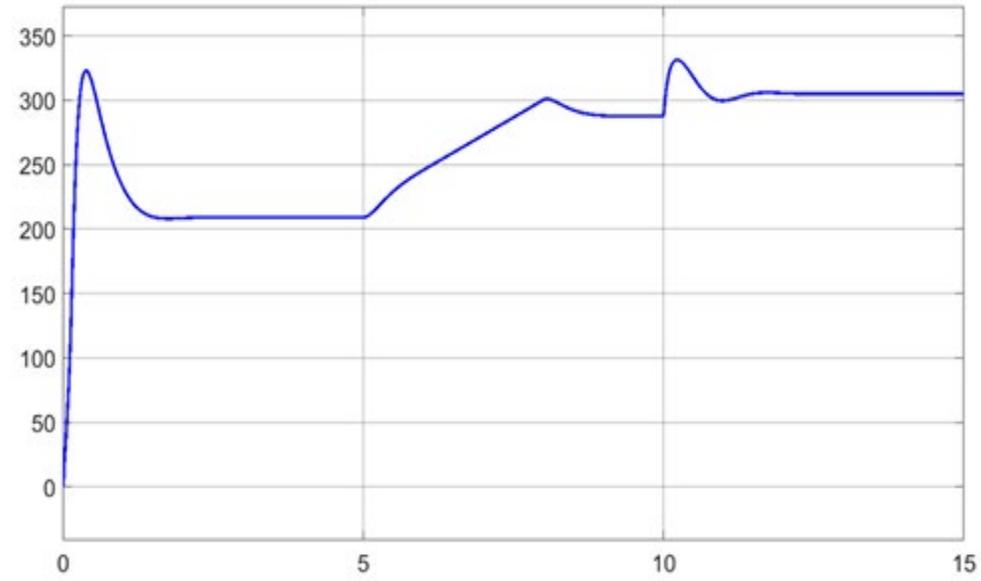
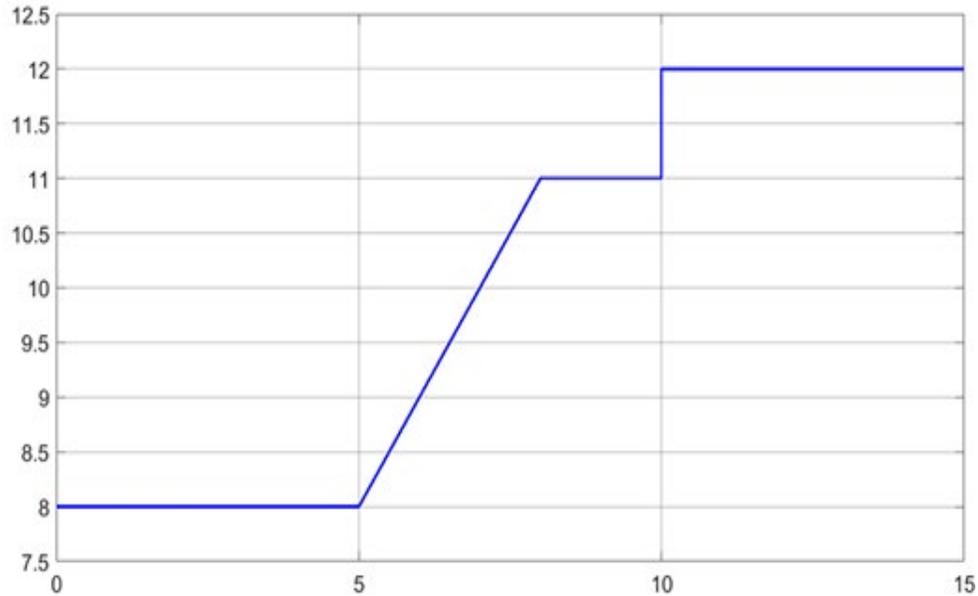
PLL



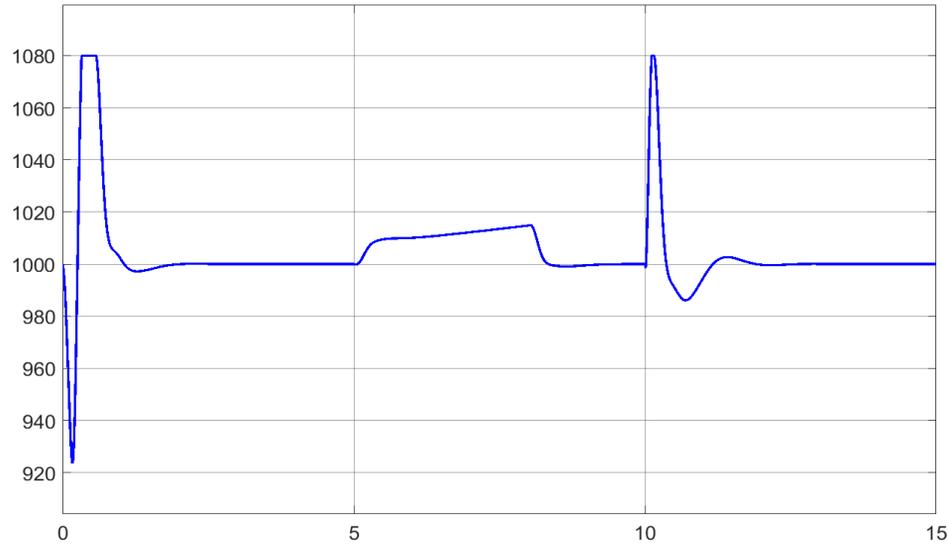
PI control in dq reference frame



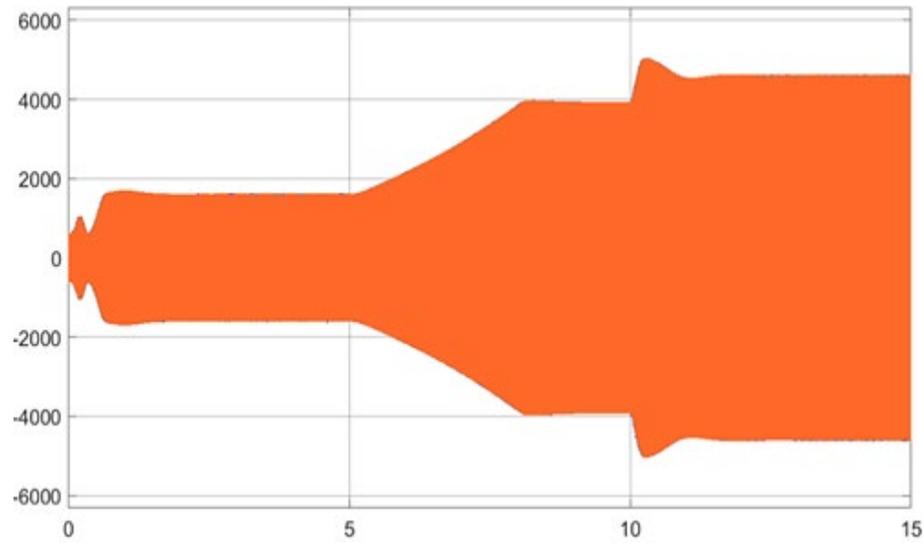
Results of simulation



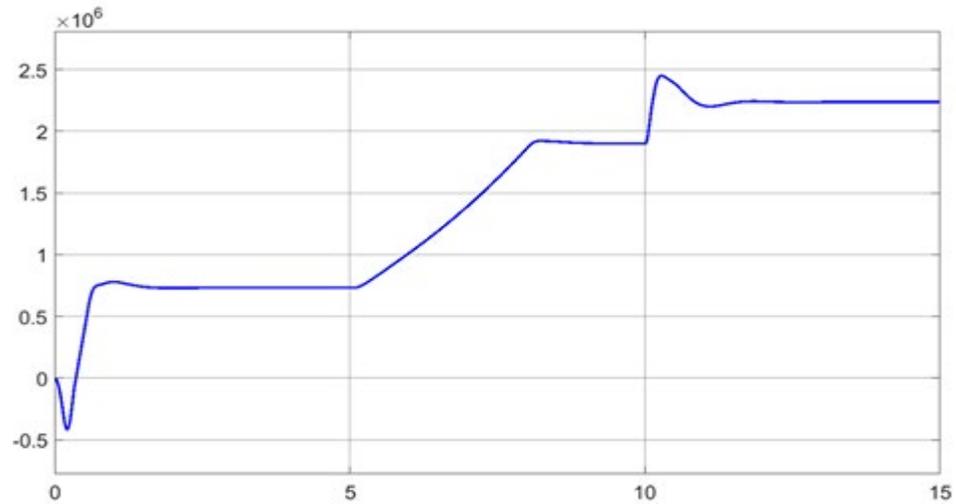
- In the pictures above, we can observe the system input wind speed and the consequential induction generator rotor speed
- Clearly, the system output shows signs of fast response, low overshoot and high overall performance



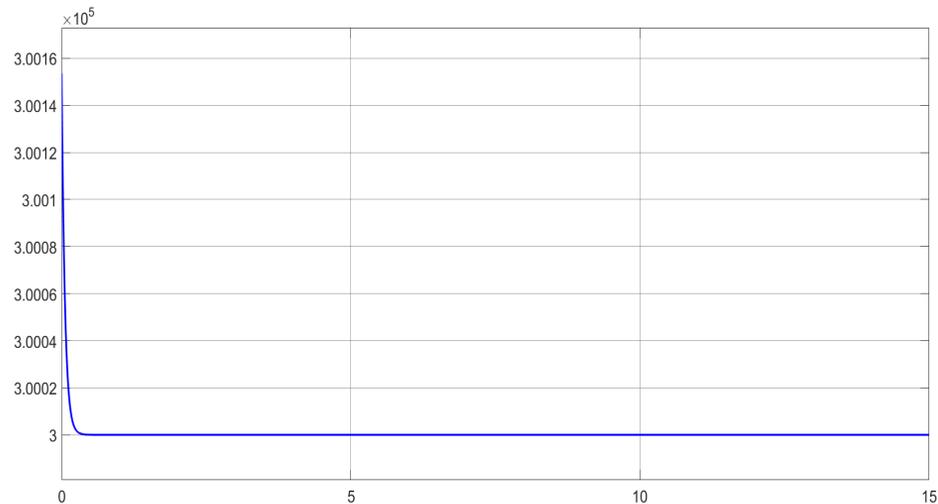
- DC link voltage is represented at the upper figure
- It follows the desired value of the capacitor voltage in a fast and smooth manner



- Current injected to the grid is represented at the lower figure
- First part is distorted due to the starting acceleration of the induction generator
- Its response to sudden changes are smooth



- Active power transferred to the grid is represented in the upper figure
- References are constant values at constant wind speed -> easy tracking with PI controller
- Low overshoot and fast response



- Reactive power transferred to the grid is represented in the upper figure
- References are constant values at constant wind speed -> easy tracking with PI controller
- Low overshoot and fast response

Thank you for your attention!